



Wednesday, 2 June 2021



AWARD

Scaling autonomous logistics

Automation in Freight Transport & Logistics: User requirements Workshop



AWARD has received funding from the European Union's Horizon 2020 research and innovation program under Grant Agreement No 101006817
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Welcome and introduction

Ted Zotos
Research and Innovation Manager,
IRU



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Agenda

09:00h-09:15h | **Welcome and introduction**

09:15h-10:00h | **Session 1: Challenges and opportunities for Future Automated Transport Logistics**

10:00h-10:10h | **Coffee break**

10:10h-11:10h | **Session 2: Defining Requirements for Key Scenarios (Breakout sessions)**

11:10h-11:50h | **Session 3: Main findings from Breakout sessions**

11:50h-12:00h | **Concluding remarks and next steps**

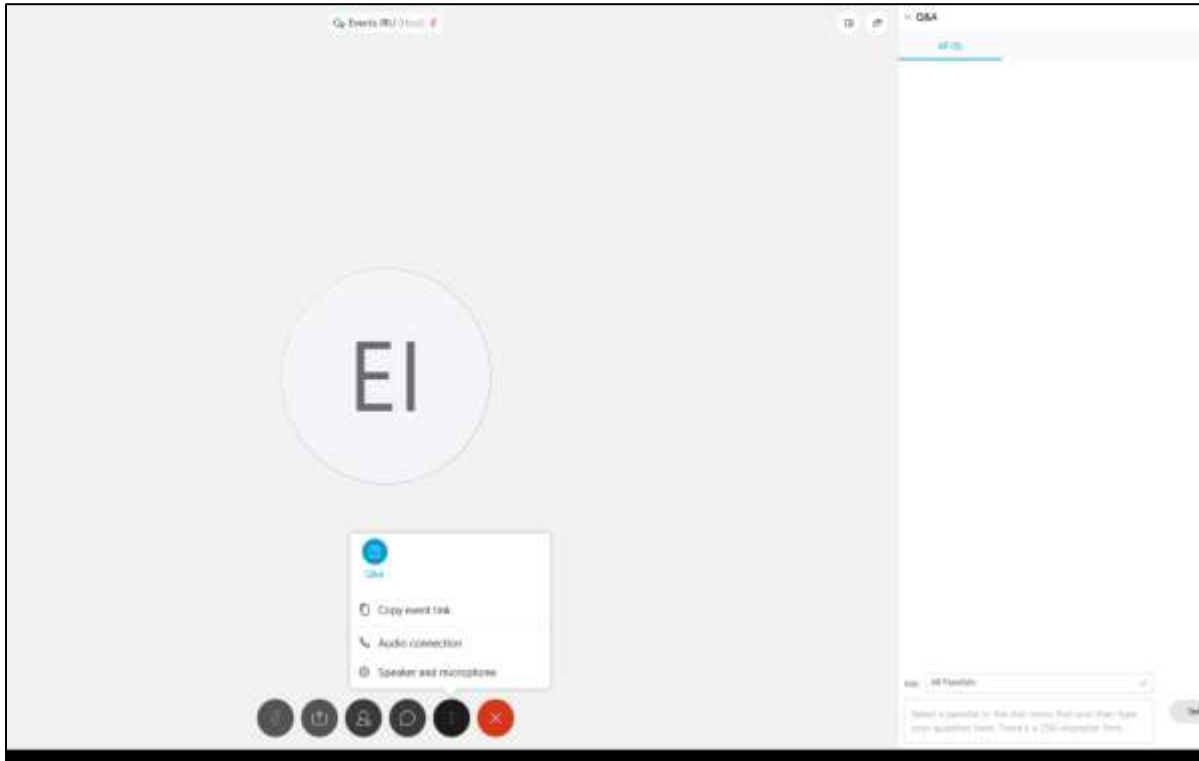


Workshop Housekeeping Rules

- Ensure you have a good internet connection
- You might want to use a headset
- You will be muted from the beginning to avoid any noises
- The chat will be public – your questions will be seen by the speakers and the audience
- Type your questions into the chat on the right of your screen
- Questions will be answered at the end of each session



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1. Microphone
2. Share screen (if permitted)
3. Participants
4. Chat
5. Additional options
6. Close and leave the event
7. Questions and Answers panel
8. Interface and visibility options

1 2 3 4 5 6

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Feel free to post in social media!

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#AutonomousLogistics, #transport, #EutransportResearch, #H2020
@award_h2020

Session 1: Challenges and Opportunities for Future Automated Transport Logistics



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Scaling Autonomous Logistics – the AWARD Approach

Inès Guth
Project Manager, EasyMile



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Contents

- H2020 context
- AWARD approach



H2020 context



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H2020 objectives – Innovation for the Industry



1. Contribution to the **accelerated deployment of innovative connected and automated freight transport solutions in Europe**
2. Contribution to the **increase of the overall safety and efficiency of freight operations** of individual trucks or fleets in confined areas and in mixed traffic (hub to hub) **through innovative connected and automated driving systems**
3. Actions will show the **uptake of new business models**
4. Actions will seek to reach a **total cost reduction of operations and logistics and supply chain**, leading to improved competitiveness of the European transport and logistics industry

“Our focus is to develop, test and demonstrate connected and **automated** systems for **heavy commercial vehicles in real logistics operations.**”



AWARD response

H2020 framework

- **2018-2020** : Digitising and Transforming European Industry and Services: Automated Road Transport
- **DT-ART-05-2020** : Efficient and safe connected and automated heavy-duty vehicles in real logistics operations

AWARD : All Weather Autonomous Real logistics operations and Demonstrations

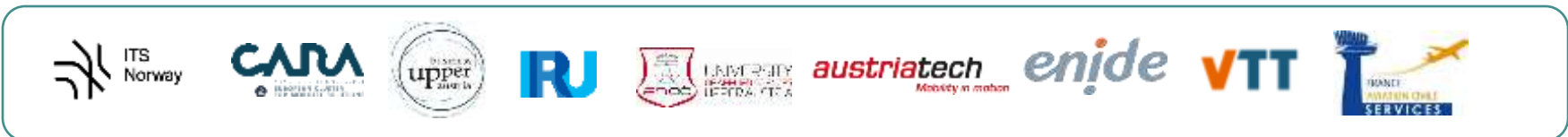
Project Coordinator : EasyMile

Partners : 29

Start of the project : 1st of January 2021



Complementary-skilled Consortium



From multiple horizons

Norway



APPLIED AUTONOMY AVINOR
ITS Norway

Finland



VTT

Denmark



DFDS

United Kingdom



NAVTECH
RADAR

Austria



AIT AUSTRIAN INSTITUTE OF TECHNOLOGY Digitrans
LEM LENS CENTER FOR AIRCRAFTS ROTAX
UNIVERSITY OF APPLIED SCIENCES austriatech
Mobility in motion
upper

Germany



Continental KAMAG

The Netherlands



TERBERG
BENSCHOP

France



EASY MILE CEREMA
CAM SAS

Belgium



KION GROUP RU

Switzerland




CERTX

Spain



enide

Israel



ADASY FORESIGHT
ottopia



AWARD approach



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Project ambitions

Ambition 1

AWARD ADS architecture **offers a unique set of sensors that enables 24/7 availability** (night and day, good or bad weather conditions), **within an extended ODDs**

ODD = Operational Design Domain

Ambition 2

By addressing 24/7 availability, the fully automated HDV will be **deployed over key pilot projects that are highly scalable and replicable** over warehouses, factories, airports and ports, **in mixed traffic in confined areas and on public roads**

Ambition 3

The new **fleet management system** will integrate **data from vehicles, logistics systems and the road infrastructure**, coordinating exchanges with different data providers to ensure economic viability of data-related business models, **while providing high-reliable and secured tool that optimizes logistics flows and ensures safety for other road users.**



Global approach

Development of the ADS

Able to **handle adverse environmental conditions** such as heavy rain, snowfall, fog

Targeting compliance with **ISO 26262** and taking into consideration **SOTIF recommendations**

Integrating **multiple sensor modalities and an embedded teleoperation system** to address **24/7 availability**

Optimized fleet management & supervision system for logistics use cases

Integration into HDV

KION



KAMAG



TLD



TERBERG



Demonstrations

Industrial autonomous loading & unloading operations



Hub to hub autonomous logistics on public roads



Airport autonomous ground support equipment



Port Trailer autonomous transfer operations



Use Case 1: Autonomous loading & unloading forklift operations

Site

Linde Aschaffenburg Material handling

Private site

Objective

To demonstrate gitter boxes transport and yarding on Linde Aschaffenburg site, using an autonomous counter-balanced forklift vehicle.



Use Case 2: Hub-to-hub shuttle service from warehouse/production site to logistics hubs

Site

Engine Factory of BRP-Rotax

Logistic Hub of DB Schenker

Public & private site

Objective

To demonstrate highly automated, continuous, hub-to-hub freight transportation between both sites, which are connected via public side roads, public crossing areas and a public main road.



Use Case 3: Automated baggage tractor on airside in Avinor OSL Gardermoen airport

Site

OSL Gardermoen airport

Private site

Objective

To demonstrate automated baggage tractor transportation under harsh-weather conditions from aircraft stand n°9 towards aircraft stand n°8 and vice – versa.

The use case will be extended with automated ULD transportation from proximity storage to the makeup area, and from the makeup area to the aircraft stand.



Use Case 4: Container transfer operations and automated boat loading in Rotterdam port

Site

Rotterdam port terminal

Restricted site

Objective

To demonstrate and validate AWARD technology on a busy Roll-in/Roll-off terminal in Rotterdam (NL). The objective is to integrate automated trailer transfer with DFDS terminal systems and operate in a live environment with other vehicles and people



02/06/221

Thank you!

Inès Guth



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Acceptance Factors for Autonomous Transport Logistics

Peter Fröhlich
Senior Scientist, AIT Austrian
Institute of Technology



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Coffee break



Session 2: Defining Requirements for Key Scenarios – Breakout sessions



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Breakout sessions

- Automated goods handling within the logistics
- Hub-to-hub transport on public roads
- Automated transport for airport baggage handling
- Automated trailer transfer with port terminal systems



Session 3: Main Findings from Breakout sessions



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Reporting back from the Breakout sessions

- Automated goods handling within the logistics
- Hub-to-hub transport on public roads
- Automated transport for airport baggage handling
- Automated trailer transfer with port terminal systems



Concluding remarks and next steps

Ted Zotos
Manager – Research and Innovation,
IRU



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Upcoming AWARD Workshops

- Testing methodology and evaluation
- Emerging business and operating models
- Regulatory and governance frameworks
- More TBD



Let's keep in touch!



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AWARD is paving the way for the roll-out of **driverless transportation**, whatever the weather conditions are. It will deploy safe and efficient **connected and automated heavy-duty vehicles** in real-life **logistics operations**.

EXCELLENCE

Real life logistic operations

AWARD is developing and operating safe autonomous transportation systems (ATS) in a wide range of real-life logistic use cases in a variety of different scenarios.

- Warehouse**
Autonomous loading and unloading forklift operations
- Hub-to-hub**
Autonomous logistics shuttle service on public road
- Airport**
Autonomous Cargo and Support Equipment movement of goods in airfreight
- Port**
Automated transfer operations and ship loading



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