



ITS WORLD CONGRESS 2022

AWARD

Scaling autonomous logistics





AWARD has received funding from the European Union's Horizon 2020 research and innovation program under Grant Agreement No 10 1006817

The content of this presentation reflects only the author's view. Neither the European Commission nor the INEA is responsible for any use that may be made of the information it contains.



Sébastien Liandrat Cerema adweather@cerema.fr



AWARD has received funding from the European Union's Horizon 2020 research and innovation program under Grant Agreement No 101006817

The content of this presentation reflects only the author's view. Neither the European Commission nor the CINEA is responsible for any use that may be made of the information it contains.



A review of the Cerema PAVIN fog & rain platform: from past and back to the future







Sébastien Liandrat adweather@cerema.fr

In Partnership With:









TRANSFORMATION BY TRANSPORTATION | #ITSWC2022



Introduction and context

- A world with autonomous vehicles?
 - Science-fiction to near future
- Regulation was proposed for level 3 automated driving systems
- Advanced scenarios but rarely in adverse weather
- Importance of tests in controlled environment
- Different levels of integration and realism
 - Numerical modeling
 Test bench evaluation
 - Virtual reality simulation
 Test track evaluation
- Test bench are essential because numerical simulators:
 - must be validated under real controlled conditions
 - In order to operate, require data that is difficult to collect



Introduction and context

Review of research work in the Cerema PAVIN fog & rain platform

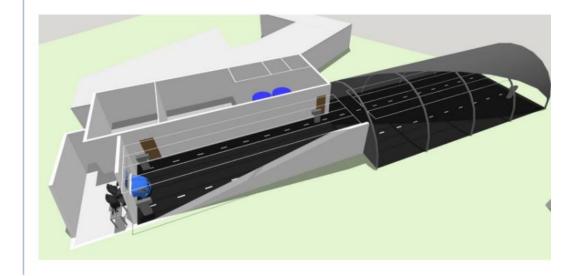
- What is Cerema?
 - French Public Agency



Liberté Égalité Fraternité



- What is the PAVIN fog & rain platform
 - Tech bench for ADAS or AV



Summary

- Introduction & context
- Origin of the PAVIN platform, the fog production
- Addition of rain production
- Today's use of the platform
- The future

Origin of the PAVIN platform, the fog production

- 80's
 - Tragic accidents in France
 - Construction of the PAVIN platform in 1983
 - Initially only fog production



- 90's
 - Intensive development of the fog system
 - Droplet Size Distribution qualification





- 00's
 - Complete review of the system
 - Two kinds of fog reproducible (Droplet Size Distribution)
- Active regulation to maintain a specific fog density (10 meters to 100 meters, +/10%)

Add of rain production

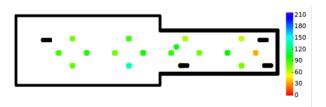
- 2007-2009
 - First system, 30 to 55 mm/h
 - Research oriented towards human perception
 - Examples: windshield aspersion, wiper system



- 2016-2019
 - H2020 DENSE project, new system, 16 to 165 mm/h
 - Better representativeness + homogeneity



- From 2015
 - Impact of rain conditions on the camera

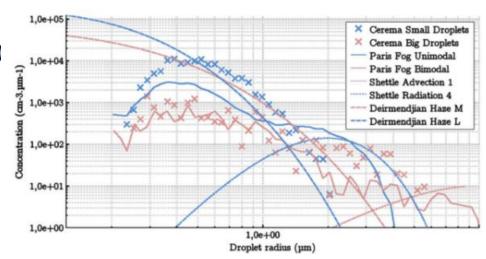


We will talk about that later...



Fog and rain features

- Fog generation with controlled density
 - Regulation between 10m to 100m (+/- 10%)
- Rain generation with controlled intensity
 - 16 mm/h to 165 mm/h
- Realistic Droplet Size Distribution
 - Rain
 - Two kinds of fog (continental or maritime)







Main applications of the PAVIN platform

- From 2010: Research on computer vision became predominant
 - Rise of ITS and the AV development

3 main areas of use of the PAVIN platform

Measurement of weather conditions by camera (AI)

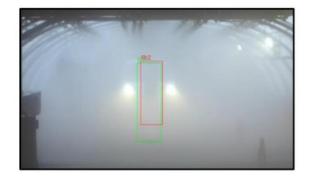
Numerical simulation of meteorological phenomena

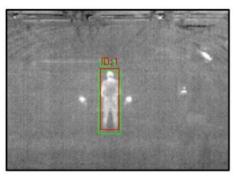
Measurement of the impact of adverse weather conditions on vehicle perception systems

Impact of adverse weather on vehicle perception systems

- Examples in the european AWARD project (2021-2024)
 - All Weather Autonomous Real logistics operations and Demonstrations
 - Innovations to the transport industry, fleet operators and the entire logistics sector
 - Different scenarios: warehouse, hub to hub, airport, port
- Easymile: Comparison of different Lidar technologies
 - Spinning, Risley prisms, micro-motion and MEMS
- Foresight Automotive: Test of its Quadsight vision system
 - 3D object detection (pedestrians and vehicles)



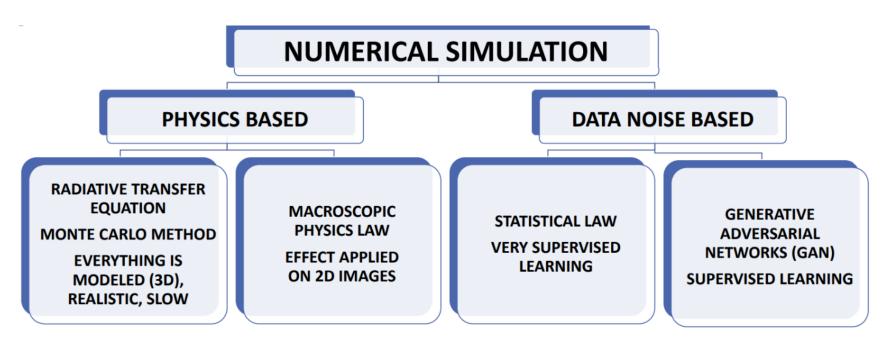




Measurement of weather conditions by camera (AI)

- First: Impact on image features
 - Rainfall intensity has proportional effect on common image features
- Then: use of Deep Convolutional Neural Networks (DCNN)
 - Single view, 90% success with WeatherEye solution
 - No possible generalization if the point of view is changed
- Now: generalization possible with multi sites
 - First learning in artificial physical conditions within the PAVIN platform
 - Transfer and fine-tuning on images that are acquired on a different real site

Numerical simulation of adverse weather



Cerema research team is working on these topics which are complementary All the model has to be validated with physical data, natural or simulated



AWARD has received funding from the European Union's Horizon 2020 research and innovation program under Grant Agreement No 101006817

The content of this presentation reflects only the author's view. Neither the European Commission nor the CINEA is responsible for any use that may be made of the information it contains.



A brand-new platform...

4 main evolutions

- **Dimensions**
 - 50 meters length
 - 7 meters width
 - 6 meters high





- Temperature stability
 - In space and time
 - Isolation and ventilation



- Illumination conditions
 - Great homogeneity
 - Artificial and natural



- Environmental exemplarity
 - Water reuse
 - Biobased materials
 - Few energy consumption

...coming up in 2024



Conclusions

- The Cerema PAVIN fog & rain platform
 - 40 years of evolution
 - Controlled conditions of adverse weather
- Involved in many major research and development projects
 - Impact on vehicle perception systems
 - Weather measurement by camera
 - Numerical simulations
- Worldwide presence
 - About 50 different sensors
 - About 15 countries in the world
- New upcoming possibilities
 - New platform
 - Digital twin

The platform can be rented for confidential private trials

Complementary-skilled Consortium

Sensors

Autonomous Driving System

Heavy-Duty Vehicles

End-users Industrial sites













ottopia













Certification and proving grounds













Impact assessment, business modelling and regulatory frameworks













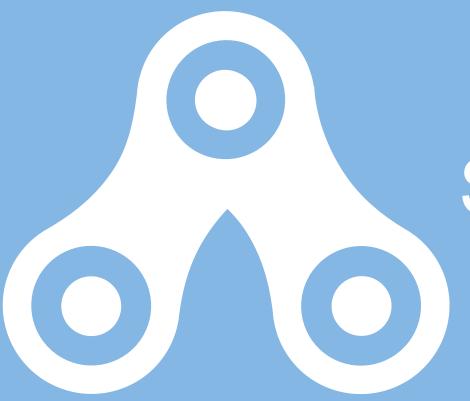












Support us!



AWARD has received funding from the European Union's Horizon 2020 research and innovation program under Grant Agreement No 101006817

The content of this presentation reflects only the author's view. Neither the European Commission nor the INEA is responsible for any use that may be made of the information it contains.

Let's keep in touch!





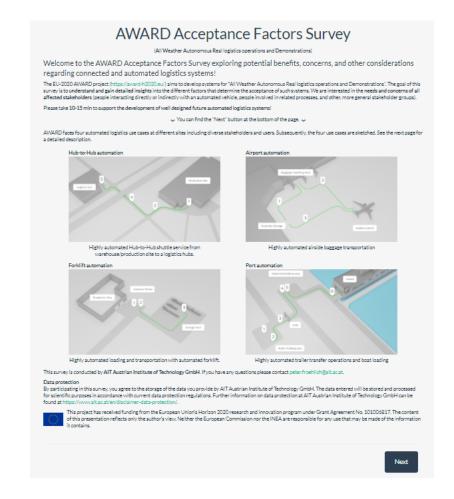
LinkedIn





Twitter

Participate to our Acceptance Factors survey!







This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 101006817.

The content of this reflects only the author's view. Neither the European Commission nor CINEA is responsible for any use that may be made of the information it contains.







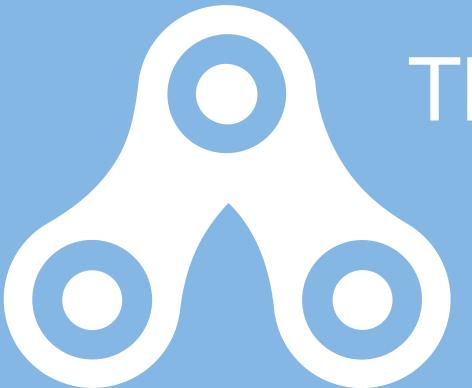








19-20/11/2022



Thank you!

DUTHON PIERRE





AWARD has received funding from the European Union's Horizon 2020 research and innovation program under Grant Agreement No 101006817

The content of this presentation reflects only the author's view. Neither the European Commission nor the INEA is responsible for any use that may be made of the information it contains.

23



AWARD

Scaling autonomous logistics







www.award-h2020.eu



This project has received funding from the European Union's Horizon 2020 research and innovation programme under Grant Agreement No. 101006817. The content of this presentation reflects only the author's view. Neither the European Commission nor the Information it contains.