



AWARD

Scaling autonomous logistics





AWARD has received funding from the European Union's Horizon 2020 research and innovation program under Grant Agreement No 101006817

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H2020 objectives – Innovation for the Industry



- Contribution to the accelerated deployment of innovative connected and automated freight transport solutions in Europe
- Contribution to the increase of the overall safety and efficiency of freight operations of individual trucks or fleets in confined areas and in mixed traffic (hub to hub) through innovative connected and automated driving systems
- 3. Actions will show the **uptake of new business models**
- Actions will seek to reach a total cost reduction of operations and logistics and supply chain, leading to improved competitiveness of the European transport and logistics industry

"Our focus is to develop, test and demonstrate connected and **automated** systems for **heavy commercial vehicles** in **real logistics operations**."

AWARD response

H2020 framework

- 2018-2020: Digitising and Transforming European Industry and Services: Automated Road **Transport**
- DT-ART-05-2020: Efficient and safe connected and automated heavy-duty vehicles in real logistics operations

AWARD: All Weather Autonomous Real logistics operations and Demonstrations

Project Coordinator: EasyMile

Partners: 29

Timeline of the project: 1st of January 2021 – 31st of December 2023





Complementary-skilled Consortium

Sensors

Autonomous Driving System

Heavy-Duty Vehicles

End-users Industrial sites











Certification and proving grounds













Impact assessment, business modelling and regulatory frameworks





















United Kingdom















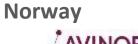
















































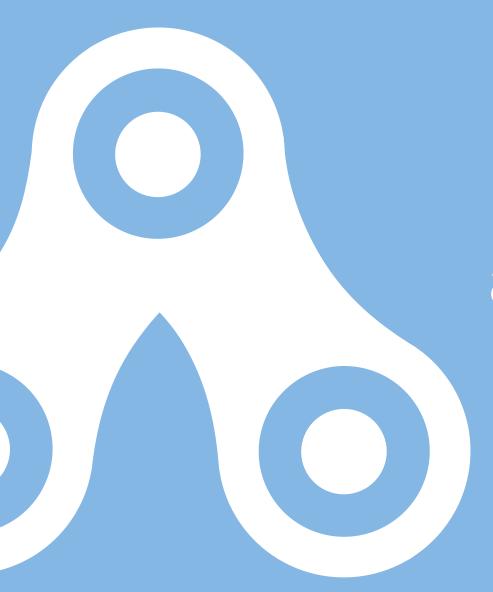
Israel











AWARD approach



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Project ambitions

Ambition 1

AWARD ADS architecture offers a unique set of sensors that enables 24/7 availability (night and day, good or bad weather conditions), within an extended ODD

ODD = Operational Design
Domain

Ambition 2

By addressing 24/7 availability, the fully automated HDV will be deployed over key pilot projects that are highly scalable and replicable over warehouses, factories, airports and ports, in mixed traffic in confined areas and on public roads

Ambition 3

The new fleet management system will integrate data from vehicles, logistics systems and the road infrastructure, coordinating exchanges with different data providers to ensure economic viability of data-related business models, while providing high-reliable and secured tool that optimizes logistics flows and ensures safety for other road users.



Global approach

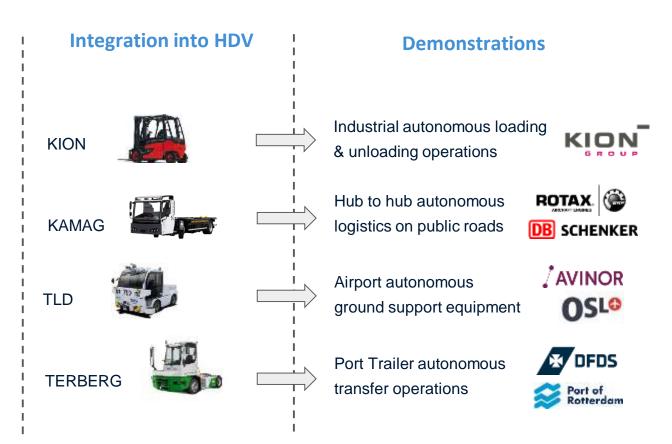
Development of the ADS

Able to handle adverse environmental conditions such as heavy rain, snowfall, fog

Targeting compliance with ISO 26262 and taking into consideration SOTIF recommendations

Integrating multiple sensor modalities and an embedded teleoperation system to address 24/7 availability

Optimized fleet management & supervision system for logistics use cases





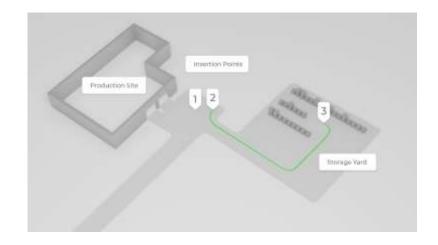
Use Case 1: Autonomous loading & unloading forklift operations

Site

Linde Aschaffeburg Material handling Private site

Objective

To demonstrate gitter boxes transport and yarding on Linde Aschaffenburg site, using an autonomous counter-balanced forklift vehicle.





Use Case 2: Hub-to-hub shuttle service from warehouse/production site to logistics hubs

Site

Engine Factory of BRP-Rotax Logistic Hub of DB Schenker Public & private site

Objective

To demonstrate highly automated, continuous, hub-to-hub freight transportation between both sites, which are connected via public side roads, public crossing areas and a public main road.





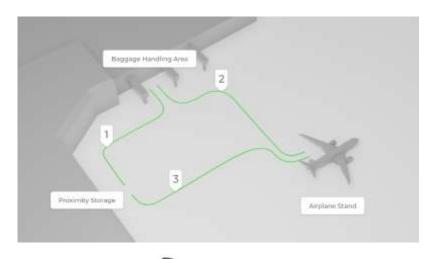
Use Case 3: Automated baggage tractor on airside in Avinor OSL Gardermoen airport

Site

OSL Gardermoen aiport Private site

Objective

To demonstrate automated baggage tractor transportation under harsh-weather conditions from proximity storage to the makeup area, and from the makeup area to the aircraft stand.





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Use Case 4: Container transfer operations and automated boat loading in Rotterdam port

Site

Rotterdam port terminal Restricted site

Objective

To demonstrate and validate AWARD technology on a busy Roll-in/Roll-off terminal in Rotterdam (NL). The objective is to integrate automated trailer transfer with DFDS terminal systems and operate in a live environment with other vehicles and people







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Thank you!



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www.award-h2020.eu



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